

Pump Controller Type ABS PC 111/211





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Installation and User Guide

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ABOUT THIS GUIDE, AUDIENCE AND CONCEPTS

| | This guide describes the pump control units PC 111/211. The only difference be- tween the two pump controllers is that PC 111 is intended for one pump whereas PC 211 can control two pumps. |
|--------------------------|--|
| Prerequisites | This guide assumes that you already are acquainted with those pumps you are set out to control and the sensors connected to PC 111/211. |
| | The pump controller can either use an analogue level-sensor, which measures the water level in the pit, for precise control over start and stop levels, or it can use simple float switches placed at start and stop levels. It is also possible to use only a start float, and let the pump(s) stop after a certain time or when the meas- ured phase angle of the motor current has changed a certain amount (indicating that the pump is running dry). |
| | An analogue level-sensor has the advantage over float switches that it is more robust (can not get stuck or be mechanically jammed), is more accurate, and is more flexible (you can easily change the start and stop levels). Also, you can get a reading of the water level in the pit. |
| | Float switches can be used in addition to an analogue level-sensor, as a backup, and as an additional alarm input. |
| | You need to know if the pump(s) should be exercised in case of long idle periods. If the installation has two pumps, you need to know if the pumps should alter- nate. |
| Reading guide | For installation, read Chapter 1 <i>Installation</i> . Before you make any settings, or use the pump controller, read Chapter 2 <i>Overview of functions and usage</i> ; it describes the general functionality and the meaning and usage of the controls on the panel. Finally, make sure that all settings according to Chapter 3 <i>Menus: status and settings</i> are suitable for your application. |
| Glossary and conventions | Text in blue indicates a hypertext link. If you read this document on a computer, you can click on the item, which will take you to the link destination. |
| | <i>Pump exercising</i> : Long idle periods in a corrosive contaminated environment are not good for pumps. As a countermeasure, they can be "exercised" at regular intervals, which will reduce corrosion and other detrimental effects. |
| | Cas m: Casine of the phase angle m between the motor current and the voltage |

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Cos ϕ : Cosine of the phase angle ϕ between the motor current and the voltage.

INSTALLATION

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1.1 Mount the controller

Mount the controller on a 35 mm DIN rail. The physical dimensions of the controller is:118 x 128 x 72 mm (H x W x D); depth from the panel surface is 55 mm. It easily snaps onto the rail, but to remove it you may need to pull/bend the tab at the side, using a screwdriver.

1.2 Connect the controller

Connect the controller according to Table 1-1 and Table 1-2. For the leakage monitors, we recommend a separate reference wire from each pump chassis to the leak. ref terminal; this will provide the best protection against magnetic induced ground currents. A simplified scheme may work in installations with small magnetic disturbances: in this case, you can use a common reference wire for both leakage monitors, provided that it is also connected to the earth/ground terminal on the pump controller.





For instance an external motor protector or a manual switch. ii. Connect the switch to + 12V. Active signal (on) blocks the pump and issues an alarm.

iii. For instance a PTC thermistor, such as Klixon, or a thermal switch.



Table 1-2. Terminals at the top side

| Usage/Description | | | | |
|--|----|--|--|--|
| For power supply to an analogue level-sensor | | | | |
| nalogue level-sensor input, 4–20 mA ⁱ | | | | |
| V reference for an analogue level-sensor | | | | |
| | | | | |
| | | | | |
| ead-acid battery for backup. Charger is included in PC 111/2 | 11 | | | |
| | | | | |
| | | | | |
| | | | | |
| elay for alarm. (Max 250 VAC, 4 A, 100 VA resistive load) | | | | |
| ormally open | | | | |
| ormally closed | | | | |
| | | | | |
| | | | | |
| elay for start/stop of Pump 1 | | | | |
| lax 250 VAC, 4 A, 100 VA resistive load) | | | | |
| elay for start/stop of Pump 2, or starting capacitor in PC 111 | ii | | | |
| | | | | |

i. Senses current in the range 4–20 mA.

ii. In PC 111, the function of the relay is to temporarily connect a starting capacitor to a single-phase motor (P1) during startup.

PC 111/211 has a current transformer for each pump, where the pump is connected so that one conductor is passed through the transformer. This makes it possible to not only measure the current consumption, but also the phase angle ($\cos \varphi$) of the current. The controller can use these values and function also as a motor protector. Therefore, if you intend to use this functionality (either the current consumption measurement or the motor protector feature), connect each pump according to the following figure:



Note that L1 must be the same phase that is connected to PC 111/211 in Table1-1.

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Figure 1-1 To exploit the feature of PC 111/211 to measure current and phase angle, connect each pump, using an external relay, according to the figure. Correct measurement of the phase angle for a 3-phase pump requires that the L1 wire is the same phase as the L1 wire connected to PC 111/211 according to Table 1-1.





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2 OVERVIEW OF FUNCTIONS AND USAGE

PC 111 and PC 211 are control units for one and two pumps respectively. These units have the same functionality in terms of their capability to control pumps and manage alarms — the only difference is that PC 211 is intended for two pumps whereas PC 111 is intended for one pump.

Figure 2-1 shows the panel of the pump controller. The main view of the two-row display dynamically shows the pit status (the level in the pit or the status of start floats) and if there are any alarms. The unit will always revert to this view after 10 minutes of inactivity in any other view.



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| Escape/Cancel | The ESC button will cancel or reset the current menu operation, or take you to the main view. | |
|----------------------------|--|--|
| The menu selection knob | The menu selection knob has two functions: | |
| | By rotating the knob in either direction, you do one of the following: Scroll through menu items. | |
| | Change the value of a menu item (the value is either a number or an item in a list of alternatives; to confirm/save the change, press the knob). | |
| | By pressing the knob, you do one of the following: | |
| | Enter into a menu. (You will then see a blinking cursor where a value can be changed.) | |
| | Confirm/save/perform a choice or an operation. | |
| | Acknowledge an alarm. | |
| | When the display shows that there is an unacknowledged alarm, press the knob to bring up a prompt to acknowledge the alarm, and if you press the knob once more, it acknowledges the alarm. | |
| | When the display shows that there is an active alarm, press the knob to bring up a list of details about the alarms; rotate the knob to scroll the list. Press ESC to go back to the main view. | |
| How to adjust the contrast | To adjust the contrast of the display, press the ESC button and rotate the knob. | |
| How to enter values | Rotate the knob to the desired value. (A value is either a number or an item in a list of alternatives.) | |
| Battery backup | PC 111/211 includes a charger for a lead-acid battery backup. During battery operation (no 230 V power), the pump relays are always off. The power indicator will remain on, and the alarm indicator will be on. The alarm relay will function according to the setting in Table 3-2 (Func Alarm Relay). | |

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3 MENUS: STATUS AND SETTINGS

This chapter describes all settings that need to be properly set before the pump controller is used. How to use the menu selection knob to enter and save values is described in Chapter 2 Overview of functions and usage.

3.1 Select language

- 1. Rotate the menu selection knob anticlockwise one step (or until you see the menu item Select Language).
- 2. Press the knob.
- 3. Scroll to the desired language by rotating the knob.
- 4. Press the knob to save the choice.

3.2 Menus: status information and all settings

The first 7 clockwise items are only intended to show the current status. Table 3-1 shows these items. The other menu items are settings you can make. Table 3-2 shows all those items.

The menu system adapts dynamically to show only those items that currently are "usable"; for instance, if Sensor Type is set to Start/Stop float rather than Analogue, you will not see the menu items for setting start and stop levels. Likewise, the menu on PC 111 will not show items related to pump 2.

| Menu item | Value | | | |
|---------------|--|--|--|--|
| Pit status | The main view, which shows the pit status (the level in the pit or the status of start floats) and alarm status. | | | |
| Current P1 | The electric current and its phase angle | | | |
| Cosine pP1 | | | | |
| Current P2 | The electric current and its phase angle. | | | |
| Cosine φ P2 | | | | |
| Run. Time P1 | The accumulated running time of the pump. | | | |
| Run. Time P2 | (This value can be edited.) | | | |
| No. Starts P1 | The accumulated number of times the pump has started. | | | |
| No. Starts P2 | (This value can be edited.) | | | |

Table 3-1. Menu items that show current status, sorted clockwise



| | Table 3-2. Setting | gs, sorted clockwl | ise (Sheet 1 of 2) | | | |
|-------------|---------------------------------|---|---|--|--|--|
| | Menu item | Value | Comment | | | |
| | Sensor Type | {Analog, Start/stop float | Choose method of level control: an analogue level-sensor or start/stop floats. | | | |
| | Scaling 100%= | Value in m/ft/bar | | | | |
| | Scaling 0%= | Value in m/ft/bar | | | | |
| | Unit | {m, ft, bar} | | | | |
| | Filter | Seconds | | | | |
| | High-Level Alarm | Chosen unit | <i>This section is for an analogue level-sensor.</i> For Unit, select the unit you will use for scaling. (For ft, you get foot with decimals, not foot/inch.) | | | |
| | Low-Level Alarm | Chosen unit | | | | |
| | Start Level P1 | Chosen unit | | | | |
| | Stop Level P1 | Chosen unit | | | | |
| | Start Level P2 | Chosen unit | | | | |
| | Stop Level P2 | Chosen unit | | | | |
| | Start Criteria | {1 float + time, 2 start floats} | Start criteria using floats with PC 211. | | | |
| | Time to Start | Seconds | Unless Start Criteria is 2 start floats, the second pump will start Time to Start seconds after the (single) float is triggered. | | | |
| | Stop Criteria | {Stop float, Time, Delta cos φ} | Stop criteria using floats. If Stop Criteria is Time, a single pump will stop Time | | | |
| | Stop Float NO/NC | {Normally open, Normally closed} | to Stop seconds after the start float releases, whereas two running pumps will stop after half that time. | | | |
| | Time to Stop | Seconds | If Stop Criteria is Delta cos φ, the pump(s) will stop when cosine of the phase angle φ has changed Delta cos φ. See note for details. | | | |
| | Delta cos œ | Value 0 –1 | | | | |
| | Alternation | {Off, Both stopped, Each pump stop} | Unless Off, it will switch to the other pump, either after each pump stop, or after both pumps have stopped. | | | |
| Only PC 111 | Start Cap. Time | Seconds | The time during which the relay P2 is activated after start of pump P1. Used to temporarily con- nect a starting capacitor to a single-phase motor during startup. Default is 1.2 seconds. | | | |
| | Start Delay | Seconds | To suppress spikes and noise, triggered thresh- | | | |
| | Stop Delay | Seconds | olds from sensors can be required to persist for a certain time before a state change is ac- cepted. | | | |
| _ | Curr. Sensor P1 | {On, Off} | | | | |
| 1 | Motor Prot. P1 | {On, Off} | PC 111/211 has a current transformer for each | | | |
| | Nominal Curr. P1 | Amperes | pump, see footnote ⁱⁱ . If no conductor is passed through the transformer, set Curr. Sensor to Off! | | | |
| P1 | Dry Run Det. P1 | {Off, Low current, Delta cos ⴔ} | Note: It is important to set Nominal Curr. to the reading you get in normal conditions! If left at | | | |
| | Low Current P1 | Amperes | zero, it disables all pump blockings and alarms | | | |
| | Delta cos œ P1 | Value 0 –1 | related to current or phase loss. | | | |
| | Curr. Sensor P2 | {On, Off} | In the group Dry Run Detect, menu item Low Cur- | | | |
| 1 | Motor Prot. P2 | {On, Off} | rent or Delta cos φ will only appear if it has been selected as the method for Dry Run Detect,. Set a | | | |
| | Nominal Curr. P2 | Amperes | value that indicates that the pump is running dry. | | | |
| P2 | Dry Run Det. P2 | {Off, Low current, Delta cos φ} | If Low Current is selected, the pump will be blocked when the current is < Low Current. If Delta cos φ is selected, the pump will be blocked when cos φ changes more than Delta cos φ | | | |
| | Low Current P2 | Amperes | | | | |
| | | Value 0 –1 | cos φ changes more than Delta cos φ. | | | |
| | Delta cos cpP2 | Value o T | If Day Dup Departies S. O. the selection shall be served of the | | | |
| l | Deita cos o P2 Dry Run Reset | Minutes | If Dry Run Reset is > 0, the alarm will be reset (and the pump deblocked) after that time. | | | |

 Table 3-2.
 Settings.
 sorted clockwise (Sheet 1 of 2)





| Menu item | Value | Comment | | | |
|-----------------------------------|---------------------------------|---|--|--|--|
| P1 Backup Start | {On, Off} | If set to On, and the high-level float turns on, th | | | |
| P2 Backup Start | {On, Off} | pump(s) will run for a period of Backup Run Time | | | |
| Backup Run Time | Seconds | after the float has turned off. | | | |
| Exercise P1 | {On, Off} | Can "exercise" the pumps if they have been | | | |
| Exercise P2 | {On, Off} | standing still for Max Still Time. If the current level is below the stop level/stop float, the pump(s) | | | |
| Exercise Time | Seconds | will run for Exercise Time, otherwise, the pump(s) | | | |
| Max Still Time | Hours | will run until stop level/stop float is reached. | | | |
| Leakage Mon. P1 | {Off, Normal, Block pump} | Leakage monitor. With Normal, an alarm will b issued when the leakage monitor conducts, b | | | |
| Leakage Mon. P2 | {Off, Normal, Block pump} | the pump will not be blocked. | | | |
| Temp. Monitor P1 | {Off, Man reset, Auto reset} | Temperature monitor, usually a PTC element. When the temperature exceeds the element's threshold, the pump will be blocked. With Auto | | | |
| Temp. Monitor P2 | {Off, Man reset, Auto reset} | reset, the alarm (and blocked state) will be reset when the temperature goes down again. With Man reset, it must be manually reset. | | | |
| Buzzer | {On, Off} | If On, and there is an unacknowledged alarm, a buzzer will sound for Max Buzzer Time or until | | | |
| Max Buzzer Time | Minutes | acknowledged. If Max Buzzer Time is zero, there is no maximum time. | | | |
| Backlight Time | Minutes | A value of zero means that the backlight will always be on. | | | |
| Func Alarm Relay | {Buzzer, Ac- tive alarm} | If set to Buzzer, the relay will follow the buzzer timer or until acknowledged. If set to Active alarm, it will be active as long as there is an active alarm. | | | |
| Password | {On, Off} | If the setting is changed, you must enter the cur- rent password. The default password is 2. | | | |
| Change Password | Integer | If you have forgotten the password, contact the distributer to unlock the controller. | | | |
| PC 111/211 Ver | Version | | | | |
| Select Language Select a language | | | | | |

Table 3-2. Settings, sorted clockwise (Sheet 2 of 2)

i. Cos ϕ is measured about 5 seconds after the pump has started. If either Stop Criteria or Dry Run Detect is set to Delta cos ϕ , then the measured value, subtracted by the chosen Delta cos ϕ , is the threshold that will stop the pump. If both functions are active, please set Delta cos ϕ for the Stop Criteria lower than Delta cos ϕ for the Dry Run Detect — the pump will then stop without Dry Run Detect issuing an alarm.

ii. The pump should be connected so that one conductor is passed through the current transformer. This enables the controller to monitor the current and issue an alarm if a measurement indicates that the pump is running dry. In addition, the controller can function as a motor protector that complies with the standard for Class 10 protectors — the time to block the motor depends on how much the current exceeds Nominal Curr. It can also measure the phase angle (cos qp).

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4 TECHNICAL DATA AND EMC COMPATIBILITY

4.1 Technical data

| Ambient operating temperature: | –20 to +50 °C |
|--------------------------------|---|
| Ambient storage temperature: | –30 to +80 °C |
| Mounting: | DIN rail 35 mm |
| Humidity: | 0–95 % RH non-condensing |
| Dimensions: | H x W x D 118 x 128 x 72 mm Depth is 55 from panel surface |
| Power supply: | 230V AC (210-250 V) |
| Power consumption: | < 30 mA 230 V AC, <120 mA 12 V DC |
| Max load on relays: | 250 VAC, 4 A, 100 VA resistive load |
| Non-analogue input voltage: | 5–34 V DC |
| Non-analogue input resistance: | 5 kohm |
| Analogue sensor: | 4–20 mA |
| Analogue input resistance: | 110 ohm |
| Temperature sensor: | PTC, limit: >3 kohm |
| Leakage sensor: | Limit: <50 kohm |
| Analogue input resolution: | 12 bits |
| Maximum length of I/O cables: | 30 meters |
| Charge current for battery: | Max 80 mA, 13.7 V DC |
| Weight | 0.45 kg |
| | |

4.2 Electromagnetic compatibility

| Description | Standard | Class | Level | Remarks | Criteria ⁱ |
|--|---------------|----------|----------|-------------------|-----------------------|
| Electrostatic discharge | EN 61000-4-2 | 4 | 15 kV | Air discharge | A |
| immunity (ESD) | EN 01000-4-2 | 4 | 8 kV | Contact discharge | A |
| Fast transient/burst immunity | EN 61000-4-4 | 4 | 4 kV | | А |
| Surge immunity 1.2/50 µs. See note " EN 61000-4-5 | 4 | 4 kV CMV | | Α | |
| | EN 61000-4-5 | 4 | 2 kV NMV | | А |
| Immunity to conducted disturbances, induced by RF fields | EN 61000-4-6 | 3 | 10 V | 150 kHz – 80 MHz | A |
| Immunity to radiated RF fields | EN 61000-4-3 | 3 | 10 V/m | 80 MHz – 1 GHz | А |
| Immunity to short inter- ruptions and voltage variations | EN 61000-4-11 | | | | A |

i. Performance criteria A = Normal performance within the specification limits.

Performance criteria B = Temporary degradation or loss of function or performance that is self-recoverable.

ii. Maximum length of I/O cables is 30 meters.







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